

SUBSEQUENT SINGULARITIES OF MEAN CONVEX MEAN CURVATURE FLOWS IN SMOOTH MANIFOLDS

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ABSTRACT. For any n -dimensional smooth manifold Σ , we show that all the singularities of the mean curvature flow with any initial mean convex hypersurface in Σ are cylindrical (of convex type) if the flow converges to a smooth hypersurface M_∞ (maybe empty) at infinity. Previously this was shown (i) for $n \leq 7$, and (ii) for arbitrary n up to the first singular time without the smooth condition on M_∞ .

1. INTRODUCTION

Singularities of mean curvature flow are unavoidable if the flow starts from a closed embedded hypersurface in Euclidean space. When the initial hypersurface is mean convex in Euclidean space, the mean curvature flow (level set flow) preserves mean convexity. So we sometimes call it mean convex mean curvature flow.

Huisken-Sinestrari obtained the convexity estimate for mean convex mean curvature flow [9–11] and the cylindrical estimate for mean curvature flow of two-convex hypersurface [11], respectively. In particular, any smooth rescaling of the singularity in the first singular time is convex by [9, 10]. B. White in [15, 16] showed that any singularity of mean convex mean curvature flow which occurs in the first singular time, must be of convex type. Here, a singular point x of the flow M_t has *convex type* if

- (1) any tangent flow at x is cylindrical, namely, a multiplicity one shrinking round cylinder $\mathbb{R}^k \times \mathbb{S}^{n-k}$ for some $k < n$.
- (2) for each sequence $x_i \in M_{t(i)}$ of regular points that converge to x ,

$$\liminf_{i \rightarrow \infty} \frac{\kappa_1(M_{t(i)}, x_i)}{H(M_{t(i)}, x_i)} \geq 0,$$

where $\kappa_1, \kappa_2, \dots, \kappa_n$ are the principal curvatures with $\kappa_1 \leq \kappa_2 \leq \dots \leq \kappa_n$, and $H = \sum_i \kappa_i > 0$. Furthermore, White [16, 18] showed that all the singularities of mean convex mean curvature flow in Euclidean space are of convex type. And see [1, 8, 14] for more results in this direction. On the other hand, Colding-Minicozzi [4] showed that the only singularities of generic mean curvature flow in \mathbb{R}^3 are spherical or cylindrical. In [3] Colding-Ilmanen-Minicozzi obtained a rigidity theorem for round cylinders in a very strong sense.

In the aspect of structure of the singular set of mean curvature flow, White [15] showed that parabolic Hausdorff dimension of the space-time singular set is $n - 1$ at most for mean convex mean curvature flow in \mathbb{R}^{n+1} . When a mean curvature flow starts from a closed embedded hypersurface in \mathbb{R}^{n+1} with only generic singularities, Colding-Minicozzi

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[5] showed that their space-time singular set is contained in finitely many compact embedded $(n-1)$ -dimensional Lipschitz submanifolds plus a set of dimension $n-2$ at most.

When the initial hypersurface is mean convex in an n -dimensional smooth manifold Σ , mean convexity is preserved by mean curvature flow $(\mathcal{M}, \mathcal{K})$ in Σ in view of [15]. Let $(\mathcal{M}', \mathcal{K}')$ be any limit flow if $n \leq 7$ or a special limit flow if $n > 7$, where $\mathcal{K}' : t \in \mathbb{R} \mapsto K'_t$ (see [16] for the definition). Then K'_t is convex for every t showed by White [16]. Furthermore, if $(\mathcal{M}', \mathcal{K}')$ is backwardly self-similar, then it is either (i) a static multiplicity 1 plane or (ii) a shrinking sphere or cylinder [16]. In this paper, we will show that K'_t is convex for every t if $(\mathcal{M}', \mathcal{K}')$ is any limit flow for $n > 7$ and the flow \mathcal{M} converges to a smooth hypersurface (maybe empty) at infinity.

Theorem 1.1. *Let $\mathcal{M} : t \in [0, \infty) \mapsto M_t$ be a mean curvature flow starting from a mean convex, smooth hypersurface in a complete smooth manifold. If $\lim_{t \rightarrow \infty} (\cup_{s > t} M_s)$ (maybe empty) is a smooth hypersurface, then all the subsequent singularities of \mathcal{M} must have convex type.*

Our proof heavily depends on Ilmanen's elliptic regularization and White's work on motion by mean curvature, where we give a delicate analysis for the second fundamental form of the corresponding translating soliton related to the considered mean curvature flow in a manifold. If either Σ has nonnegative Ricci curvature or Σ is simply connected with nonpositive sectional curvature, we can remove the smooth condition on the hypersurface $\lim_{t \rightarrow \infty} (\cup_{s > t} M_s)$, and get the same conclusion (see Corollary 3.3). This can be thought of as a generalization of Theorem 3 of White [18]. After this paper, Haslhofer-Hershkovits [7] got structure theorem of singularities of mean convex mean curvature flows in Riemannian manifolds by another method independently, where even they do not need the smooth condition of the flows at infinity.

2. TRANSLATING SOLITONS FOR MEAN CURVATURE FLOW

Let (Σ, σ) be an n -dimensional smooth complete manifold with Riemannian metric $\sigma = \sum_{i,j=1}^n \sigma_{ij} dx_i dx_j$ in a local coordinate. Let N denote the product space $\Sigma \times \mathbb{R}$ with the product metric

$$\sigma + dt^2 = \sum_{i,j} \sigma_{ij} dx_i dx_j + dt^2.$$

Let $\langle \cdot, \cdot \rangle$ and $\bar{\nabla}$ denote the inner product and the Levi-Civita connection of N with respect to its metric, respectively. Set (σ^{ij}) be the inverse matrix of (σ_{ij}) . Let ∂_{x_i} and E_{n+1} be the dual frame of dx_i and dt , respectively. Denote $Df = \sum_{i,j} \sigma^{ij} f_i \partial_{x_j}$ and $|Df|^2 = \sum_{i,j} \sigma^{ij} f_i f_j$ for any C^1 -function f on Σ . Let div_Σ be the divergence of Σ . Let R and Ric denote the curvature tensor and Ricci curvature of Σ , respectively. Let \bar{R} and \bar{Ric} be the curvature tensor and the Ricci curvature of $N = \Sigma \times \mathbb{R}$, respectively.

Let S be an n -dimensional smooth graph in $\Sigma \times \mathbb{R}$ with the graphic function u and the induced metric g . In a local coordinate, $g = g_{ij} dx_i dx_j = (\sigma_{ij} + u_i u_j) dx_i dx_j$, and then $g^{ij} = \sigma^{ij} - \frac{u^i u^j}{1 + |Du|^2}$, where $u^i = \sigma^{jk} u_k$. Let Δ, ∇ be the Laplacian and Levi-Civita connection of (S, g) , respectively. Let ν denote the unit normal vector field of M in N defined by

$$(2.1) \quad \nu = \frac{1}{\sqrt{1 + |Du|^2}} (-Du + E_{n+1}).$$

Now we assume that S is a translating soliton satisfying the following equation

$$(2.2) \quad H + \lambda \langle E_{n+1}, \nu \rangle = 0$$

for some constant $\lambda > 0$. The equation (2.2) is equivalent to

$$(2.3) \quad \operatorname{div}_\Sigma \left(\frac{Du}{\sqrt{1+|Du|^2}} \right) + \frac{\lambda}{\sqrt{1+|Du|^2}} = 0.$$

In a local coordinate, the equality (2.3) can be rewritten as

$$(2.4) \quad \sum_{i,j=1}^n \left(\sigma^{ij} - \frac{u^i u^j}{1+|Du|^2} \right) u_{i,j} + \lambda = 0,$$

where $u_{i,j}$ is the covariant derivative on Σ with respect to $\partial_{x_i}, \partial_{x_j}$. Analog to Theorem 4.3 in [19], S is an area-minimizing hypersurface with the weight $e^{-\lambda x_{n+1}}$ in $\Sigma \times \mathbb{R}$. By $\nabla u = Du - \langle Du, \nu \rangle \nu$ and (2.1), we get

$$(2.5) \quad \langle E_{n+1}, \nabla u \rangle = -\langle Du, \nu \rangle \langle E_{n+1}, \nu \rangle = \frac{|Du|^2}{1+|Du|^2} = |\nabla u|^2.$$

Choose a local orthonormal frame field $\{e_i\}_{i=1}^n$ in S , which is a normal basis at the considered point. Set the coefficients of the second fundamental form $h_{ij} = \langle \bar{\nabla}_{e_i} e_j, \nu \rangle$ and the squared norm of the second fundamental form $|A|^2 = \sum_{i,j} h_{ij} h_{ij}$. Then the mean curvature $H = \sum_i h_{ii}$. Denote $\nabla_i = \nabla_{e_i}$ and $\bar{R}_{\nu j i k} = \langle \bar{R}_{\nu j} e_i, e_k \rangle = \langle -\bar{\nabla}_\nu \bar{\nabla}_{e_j} e_i + \bar{\nabla}_{e_j} \bar{\nabla}_\nu e_i + \bar{\nabla}_{[\nu, e_j]} e_i, e_k \rangle$. From (2.2) and Codazzi equation $h_{jk,i} - h_{ji,k} = -\bar{R}_{\nu j k i}$, we have

$$(2.6) \quad \begin{aligned} \nabla_i \nabla_j H &= -\lambda \nabla_i \langle E_{n+1}, \nabla_{e_j} \nu \rangle = \lambda \nabla_i (\langle E_{n+1}, e_k \rangle h_{jk}) \\ &= \lambda \langle E_{n+1}, \nu \rangle h_{ik} h_{jk} + \lambda \langle E_{n+1}, e_k \rangle h_{jk,i} \\ &= \lambda \langle E_{n+1}, \nu \rangle h_{ik} h_{jk} + \lambda \langle E_{n+1}, e_k \rangle h_{ji,k} - \lambda \langle E_{n+1}, e_k \rangle \bar{R}_{\nu j k i} \\ &= \lambda \langle E_{n+1}, \nu \rangle h_{ik} h_{jk} + \lambda \langle E_{n+1}, \nabla h_{ij} \rangle - \lambda \langle E_{n+1}, e_k \rangle \bar{R}_{\nu j k i}. \end{aligned}$$

By Simons' identity (see [20] for instance), we have

$$(2.7) \quad \begin{aligned} \Delta h_{ij} &= \nabla_i \nabla_j H + H h_{ik} h_{jk} - |A|^2 h_{ij} + H \bar{R}_{\nu i \nu j} - h_{ij} \bar{Ric}(\nu, \nu) \\ &\quad + \bar{R}_{k i k p} h_{jp} + \bar{R}_{k j k p} h_{ip} + \bar{R}_{k i j p} h_{kp} + \bar{R}_{p j i k} h_{kp} + \bar{\nabla}_k \bar{R}_{\nu j i k} + \bar{\nabla}_i \bar{R}_{\nu k j k}. \end{aligned}$$

From (2.2), substituting (2.6) to (2.7) we get

$$(2.8) \quad \begin{aligned} \Delta h_{ij} &= \lambda \langle E_{n+1}, \nabla h_{ij} \rangle - |A|^2 h_{ij} - \lambda \langle E_{n+1}, e_k \rangle \bar{R}_{\nu j k i} + H \bar{R}_{\nu i \nu j} - h_{ij} \bar{Ric}(\nu, \nu) \\ &\quad + \bar{R}_{k i k p} h_{jp} + \bar{R}_{k j k p} h_{ip} + \bar{R}_{k i j p} h_{kp} + \bar{R}_{p j i k} h_{kp} + \bar{\nabla}_k \bar{R}_{\nu j i k} + \bar{\nabla}_i \bar{R}_{\nu k j k}. \end{aligned}$$

Since N is a product manifold with the product metric, then $\langle \bar{R}_{\nu j} e_i, E_{n+1} \rangle = 0$ by Appendix A of [13]. Hence

$$-\lambda \langle E_{n+1}, e_k \rangle \bar{R}_{\nu j k i} = \lambda \langle \bar{R}_{\nu j} e_i, E_{n+1} - \langle E_{n+1}, \nu \rangle \nu \rangle = -\lambda \langle E_{n+1}, \nu \rangle \langle \bar{R}_{\nu j} e_i, \nu \rangle = H \bar{R}_{\nu j i \nu}.$$

Then we obtain

$$(2.9) \quad \begin{aligned} \Delta h_{ij} &= \lambda \langle E_{n+1}, \nabla h_{ij} \rangle - |A|^2 h_{ij} - h_{ij} \bar{Ric}(\nu, \nu) \\ &\quad + \bar{R}_{k i k p} h_{jp} + \bar{R}_{k j k p} h_{ip} + 2 \bar{R}_{k i j p} h_{kp} + \bar{\nabla}_k \bar{R}_{\nu j i k} + \bar{\nabla}_i \bar{R}_{\nu k j k}. \end{aligned}$$

and

$$(2.10) \quad \Delta H = \lambda \langle E_{n+1}, \nabla H \rangle - (|A|^2 + \bar{Ric}(\nu, \nu)) H.$$

Let η be a smooth function on \mathbb{R} satisfying that $\eta(t) = t$ for $t \in (-\infty, 1]$, $1 \leq \eta \leq 2$ on $(1, 3)$, $\eta \equiv 2$ on $[3, \infty)$, $0 \leq \eta' \leq 1$ and $\eta'' \leq 0$ on \mathbb{R} . Set $\eta_\alpha(t) = \alpha\eta(\frac{t}{\alpha})$ on \mathbb{R} for any $\alpha > 0$. Assume that Ω is a domain in Σ with positive mean curvature boundary $\partial\Omega$. Then there is an area-minimizing hypersurface $S_{\lambda,\alpha}$ with the weight $e^{-\lambda\eta_\alpha(x_{n+1})}$ in $\Omega \times \mathbb{R}$ with $\partial S_{\lambda,\alpha} = \partial\Omega \times \{0\}$ for $\lambda > 0$. Note that η_α has a finite upper bound, so it is not hard to see that $S_{\lambda,\alpha}$ is compact. In particular, $S_{\lambda,\alpha}$ satisfies the following equation

$$(2.11) \quad H + \lambda\eta'_\alpha \langle E_{n+1}, \nu \rangle = 0,$$

where ν is the unit normal vector of $S_{\lambda,\alpha}$. If $S_{\lambda,\alpha}$ is a graph over some open set with the graphic function w , the equation (2.11) can be rewritten as

$$(2.12) \quad \sum_{i,j=1}^n \left(\sigma^{ij} - \frac{w^i w^j}{1 + |Dw|^2} \right) w_{i,j} + \lambda\eta'_\alpha(w) = 0$$

in a local coordinate.

Now let's show that $S_{\lambda,\alpha}$ is a graph over Ω by White's argument [18]. Let $S_{\lambda,\alpha}(t) = \{X - tE_{n+1} \mid X \in S_{\lambda,\alpha}\}$ for any $t \in \mathbb{R}$. Let t_m be the smallest nonnegative number such that $S_{\lambda,\alpha}(t_m)$ intersects $S_{\lambda,\alpha}$ in the interior. If $t_m = 0$, then clearly $S_{\lambda,\alpha}$ is a graph. If $t_m > 0$, the two hypersurfaces $S_{\lambda,\alpha}$ and $S_{\lambda,\alpha}(t_m)$ touch at an interior point $X = (x, t) \in \Omega \times \mathbb{R}$. Hence the tangent cones to $S_{\lambda,\alpha}$ and to $S_{\lambda,\alpha}(t_m)$ at X , respectively, both lie in halfspaces and are therefore a same hyperplane. So X is a regular point of $S_{\lambda,\alpha}$ and $S_{\lambda,\alpha}(t_m)$, respectively. $S_{\lambda,\alpha}(t_m)$ satisfies the equation

$$H + \lambda\eta'_\alpha(\cdot + t_m) \langle E_{n+1}, \nu \rangle = 0.$$

Namely, $S_{\lambda,\alpha}(t_m)$ can be written as a graph over some neighborhood of x with a graphic function \tilde{w} satisfying

$$(2.13) \quad \sum_{i,j=1}^n \left(\sigma^{ij} - \frac{\tilde{w}^i \tilde{w}^j}{1 + |D\tilde{w}|^2} \right) \tilde{w}_{i,j} + \lambda\eta'_\alpha(\tilde{w} + t_m) = 0.$$

Let $\varphi = w - \tilde{w}$, then $\varphi = 0$ at x and $\varphi \geq 0$ in some neighborhood of x as $S_{\lambda,\alpha}(t_m)$ is below $S_{\lambda,\alpha}$. Moreover,

$$(2.14) \quad \begin{aligned} & \sum_{i,j} \left(\sigma^{ij} - \frac{\partial^i w \partial^j w}{1 + |Dw|^2} \right) \varphi_{i,j} = -\lambda\eta'_\alpha(w) - \sum_{i,j} \left(\sigma^{ij} - \frac{\partial^i w \partial^j w}{1 + |Dw|^2} \right) \tilde{w}_{i,j} \\ &= -\lambda\eta'_\alpha(w) + \lambda\eta'_\alpha(\tilde{w} + t_m) + \sum_{i,j} \left(\frac{\partial^i w \partial^j w}{1 + |Dw|^2} - \frac{\partial^i \tilde{w} \partial^j \tilde{w}}{1 + |D\tilde{w}|^2} \right) \tilde{w}_{i,j} \\ &= -\lambda\eta'_\alpha(w) + \lambda\eta'_\alpha(\tilde{w} + t_m) + \sum_{i,j} \left(\frac{\partial^i w \partial^j w - \partial^i \tilde{w} \partial^j \tilde{w}}{1 + |D\tilde{w}|^2} + \frac{\partial^i w \partial^j w}{1 + |Dw|^2} - \frac{\partial^i w \partial^j w}{1 + |D\tilde{w}|^2} \right) \tilde{w}_{i,j} \\ &= -\lambda\eta'_\alpha(w) + \lambda\eta'_\alpha(\tilde{w} + t_m) + \sum_{i,j} \frac{\partial^i \varphi \partial^j w + \partial^i \tilde{w} \partial^j \varphi}{1 + |D\tilde{w}|^2} \tilde{w}_{i,j} \\ & \quad - \frac{\partial^i w \partial^j w}{(1 + |Dw|^2)(1 + |D\tilde{w}|^2)} \langle D(w + \tilde{w}), D\varphi \rangle. \end{aligned}$$

Combining $\eta''_\alpha \leq 0$ and $t_m > 0$, we conclude that $S_{\lambda,\alpha}$ and $S_{\lambda,\alpha}(t_m)$ lie in parallel vertical planes by the strong maximum principle at x . However, it is impossible. So $S_{\lambda,\alpha}$ is a smooth graph over Ω , which minimizes the weighted area with the weight $e^{-\lambda\eta_\alpha(x_{n+1})}$ and with boundary $\partial\Omega \times \{0\}$ in $\Omega \times \mathbb{R}$. Moreover, if $u_{\lambda,\alpha}$ is the graphic function of $S_{\lambda,\alpha}$, then $u_{\lambda,\alpha} \geq 0$ by maximum principle.

Set $d(x) = d(x, \partial\Omega)$ for all $x \in \Omega$, and $\Omega_t = \{x \in \Omega \mid d(x) > t\}$ for $t \geq 0$. There is a constant $0 < \epsilon < 1$ such that $\partial\Omega_t$ is smooth with mean curvature $\mathcal{H}(x, t) \geq \epsilon$ for any $x \in \partial\Omega_t$ and $0 \leq t < \epsilon$, and d is smooth on $\Omega \setminus \Omega_\epsilon$.

Lemma 2.1. *Let $u_{\lambda, \alpha}$ be a smooth solution to (2.12) on $\overline{\Omega}$ with $u_{\lambda, \alpha} = 0$ on $\partial\Omega$ for any $\lambda, \alpha > 0$, then we have the following boundary gradient estimate:*

$$|Du_{\lambda, \alpha}| \leq \epsilon^{-1}(\lambda + 1) \quad \text{on } \partial\Omega.$$

Proof. Let $\{e_i\}_{i=1}^n$ be an orthonormal vector field tangent to $\partial\Omega_t$ at a considered point $x \in \partial\Omega_t$, and denote e_n be the unit normal vector field to $\partial\Omega_t$ so that e_n points into Ω_t . Since d is a constant on $\partial\Omega_t$, then at x we get

$$(2.15) \quad \sum_{i=1}^{n-1} (D_{e_i} D_{e_i} - (D_{e_i} e_i)^T) d = 0,$$

and $(D_{e_n} D_{e_n} - D_{e_n} e_n) d = 0$, where $(\cdots)^T$ denotes the projection into the tangent bundle of $\partial\Omega_t$. Hence at x one has

$$(2.16) \quad \begin{aligned} \Delta_\Sigma d &= \sum_{i=1}^n (D_{e_i} D_{e_i} - D_{e_i} e_i) d = - \sum_{i=1}^{n-1} \langle D_{e_i} e_i, e_n \rangle D_{e_n} d + (D_{e_n} D_{e_n} - D_{e_n} e_n) d \\ &= - \sum_{i=1}^{n-1} \langle D_{e_i} e_i, e_n \rangle = -\mathcal{H}(x, t). \end{aligned}$$

Set $\Phi = \phi(d) = -(\lambda + 1) \log(1 - \epsilon^{-1}d)$. Then $\phi' = (\lambda + 1)(\epsilon - d)^{-1}$ and $\phi'' = (\lambda + 1)(\epsilon - d)^{-2}$. Together with (2.3), (2.16) and $\mathcal{H} \geq \epsilon$, on $\Omega \setminus \Omega_\epsilon$ we conclude that

$$(2.17) \quad \begin{aligned} \operatorname{div}_\Sigma \left(\frac{D\Phi}{\sqrt{1 + |D\Phi|^2}} \right) &= \operatorname{div}_\Sigma \left(\frac{\phi' Dd}{\sqrt{1 + |\phi'|^2}} \right) = \frac{\phi'}{\sqrt{1 + |\phi'|^2}} \Delta_\Sigma d + \frac{\phi''}{(1 + |\phi'|^2)^{\frac{3}{2}}} \\ &= \frac{-\mathcal{H}}{\sqrt{1 + (\lambda + 1)^{-2}(\epsilon - d)^2}} + \frac{(\lambda + 1)^{-2}(\epsilon - d)}{(1 + (\lambda + 1)^{-2}(\epsilon - d)^2)^{\frac{3}{2}}} \\ &\leq \frac{-\epsilon}{\sqrt{1 + (\lambda + 1)^{-2}(\epsilon - d)^2}} + \frac{\epsilon(\lambda + 1)^{-2}}{(1 + (\lambda + 1)^{-2}(\epsilon - d)^2)^{\frac{3}{2}}} \leq \frac{-\lambda(\lambda + 1)^{-1}\epsilon}{\sqrt{1 + (\lambda + 1)^{-2}(\epsilon - d)^2}} \\ &\leq \frac{-\lambda(\lambda + 1)^{-1}(\epsilon - d)}{\sqrt{1 + (\lambda + 1)^{-2}(\epsilon - d)^2}} = \frac{-\lambda}{\sqrt{1 + |D\Phi|^2}}. \end{aligned}$$

Assume that $u_{\lambda, \alpha}$ is a smooth solution to (2.12) on $\overline{\Omega}$ with $u_{\lambda, \alpha} = 0$ on $\partial\Omega$ for any $\lambda, \alpha > 0$. Analog to (2.14), $0 \leq u_{\lambda, \alpha} \leq \Phi$ on $\Omega \setminus \Omega_\epsilon$ by comparison principle. Then

$$(2.18) \quad |Du_{\lambda, \alpha}| \leq |D\Phi| = \epsilon^{-1}(\lambda + 1) \quad \text{on } \partial\Omega.$$

□

For $\alpha > 0$,

$$(2.19) \quad \frac{\partial}{\partial \alpha} \eta_\alpha(t) = \eta\left(\frac{t}{\alpha}\right) - \frac{t}{\alpha} \eta'\left(\frac{t}{\alpha}\right) = - \int_0^{\frac{t}{\alpha}} \tau \eta''(\tau) d\tau \geq 0.$$

Similar to (2.14), we conclude that $S_{\lambda, \beta}$ is above $S_{\lambda, \alpha}$ for any $\beta > \alpha$. Letting $\alpha \rightarrow \infty$, the graph $S_{\lambda, \alpha}$ converges to a generalized graph S_λ over Ω . Namely, let $u_\lambda = \lim_{\alpha \rightarrow \infty} u_{\lambda, \alpha} \geq 0$, then $S_\lambda = \partial\{(x, t) \mid u_\lambda(x) < t\}$ and u_λ is the graphic function of S_λ . Note that $\{u_\alpha = \infty\}$ may be not empty, i.e., S_λ may be not compact. Moreover, S_λ is smooth and satisfies the

equation (2.2) on $\{u_\alpha < \infty\}$. Obviously, S_λ is an area-minimizing hypersurface with the weight $e^{-\lambda x_{n+1}}$ in $\Omega \times \mathbb{R}$ with boundary $\partial\Omega \times \{0\}$.

3. PROOF OF THE MAIN THEOREM

Let Ω be a bounded domain in an n -dimensional smooth manifold Σ with smooth mean convex boundary. Assume that $\partial\Omega$ is not a minimal hypersurface in Σ . From [15], there is a mean curvature (level set) flow $\mathcal{M} : t \in [0, \infty) \mapsto M_t$ with $M_0 = \partial\Omega$. By maximum principle, there is a sufficiently small constant $\epsilon_0 > 0$ such that M_t has positive mean curvature everywhere for all $0 < t \leq \epsilon_0$. Without loss of generality, we assume that $\partial\Omega$ has positive mean curvature everywhere.

Denote $F_t(\Omega)$ be a domain in Ω with $\partial F_t(\Omega) = M_t$ for $t \in [0, \infty)$. By [15], $F_t(\Omega)$ is mean convex for each $t \in [0, \infty)$, and $M_t \cap M_{t+\tau} = \emptyset$, $F_{t+\tau}(\Omega) \subset \text{interior}(F_t(\Omega))$ for all $0 \leq t < t + \tau < \infty$. Let $v : \bigcup_{t \geq 0} M_t \rightarrow \mathbb{R}$ be the function such that $v(x) = t$ for each $x \in M_t$. Then v satisfies

$$(3.1) \quad \operatorname{div}_\Sigma \left(\frac{Dv}{|Dv|} \right) + \frac{1}{|Dv|} = 0$$

in the viscosity sense. Set $\Omega_\infty = \bigcap_{t > 0} F_t(\Omega)$ and $M_\infty = \partial\Omega_\infty$. By [15], M_∞ (maybe empty) has finitely many connected components, and the boundary of each component is a stable minimal variety whose singular set has Hausdorff dimension $\leq n - 8$. Let the parabolic Hausdorff dimension of a set $E \subset \Sigma \times \mathbb{R}$ be the Hausdorff dimension of E with respect to parabolic distance

$$\operatorname{dist}_P((x, t), (y, \tau)) = \max\{d(x, y), |t - \tau|^{1/2}\},$$

where $d(\cdot, \cdot)$ is the distance function on Σ . Let $\tilde{\mathcal{S}}$ be the spacetime singular set of \mathcal{M} defined in [15]. Then the parabolic Hausdorff dimension of $\tilde{\mathcal{S}}$ is at most $n - 2$ by [15]. Denote $\mathcal{S} = \{x \in \Omega \mid \text{there exists a } t > 0 \text{ such that } (x, t) \in \tilde{\mathcal{S}}\}$.

Now we assume that M_∞ is smooth. Then the mean curvature flow M_t converges smoothly M_∞ as $t \rightarrow \infty$. So there is an open set K with $\overline{K} \subset \Omega \setminus \Omega_\infty$ such that $\overline{\mathcal{S}} \subset K$ and v is smooth on $\overline{K} \setminus \mathcal{S}$.

From the previous argument, there is a translating soliton S_λ whose graphic function u_λ is a generalized function on Ω satisfying (2.3) on $\{u_\lambda < \infty\}$ and $u_\lambda = 0$ on $\partial\Omega$ for any $\lambda > 0$. Then

$$t \in \mathbb{R} \rightarrow (S_\lambda)_t \triangleq \operatorname{graph}(u_\lambda - \lambda t)$$

is a family of smooth hypersurfaces in $\Omega \times \mathbb{R}$ moving by mean curvature. Analog to the proof of Theorem 3 in [18], set $U_\lambda : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$U_\lambda(x, y) = \lambda^{-1} (u_\lambda(x) - y),$$

and $U : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$U(x, y) = v(x).$$

As $\lambda \rightarrow \infty$, the mean curvature flows $t \in [0, \infty) \rightarrow (S_\lambda)_t$ converge as Brakke flows to the flow $t \rightarrow M_t \times \mathbb{R}$ by elliptic regularization [12] and uniqueness of viscosity solution v . Since $U_\lambda^{-1}(t) \cap \{y = \tau\} = (S_\lambda)_t \cap \{y = \tau\}$ and $v^{-1}(t) \cap \{y = \tau\} = M_t$ for all $t, \tau \geq 0$, then U_λ converges as $\lambda \rightarrow \infty$ uniformly to U on \overline{K} . Namely, $\lambda^{-1}u_\lambda$ converges uniformly to v on \overline{K} . By the local regularity theorem in [17] (or by Brakke's regularity theorem in [2]), $\lambda^{-1}u_\lambda$ converges as $\lambda \rightarrow \infty$ to v smoothly on $\overline{K} \setminus \mathcal{S}$.

Let H_λ be the mean curvature of S_λ . By

$$H_\lambda = -\frac{\lambda}{\sqrt{1+|Du_\lambda|^2}} = -\frac{1}{\sqrt{\lambda^{-2} + \lambda^{-2}|Du_\lambda|^2}},$$

and $\lambda^{-1}u_\lambda$ converges uniformly to v on \overline{K} , there is a small constant $0 < \delta < 1$ independent of $\lambda \geq 1$ such that

$$(3.2) \quad H_\lambda \leq -\delta \quad \text{on } \overline{K} \text{ for every } \lambda \geq 1.$$

Denote $|A_\lambda|^2$ be the square norm of the second fundamental form of S_λ . Choose a local orthonormal frame field $\{e_i\}_{i=1}^n$ in S_λ , which is a normal basis at the considered point. Combining (2.9) and (2.10), for any constant γ we obtain

$$(3.3) \quad \begin{aligned} \Delta(h_{ij} + \gamma H_\lambda) &= \langle \lambda E_{n+1}, \nabla(h_{ij} + \gamma H_\lambda) \rangle - (|A_\lambda|^2 + \overline{Ric}(\nu, \nu))(h_{ij} + \gamma H_\lambda) \\ &\quad + \overline{R}_{kikp}h_{jp} + \overline{R}_{kjkp}h_{ip} + 2\overline{R}_{kijp}h_{kp} + \overline{\nabla}_k \overline{R}_{\nu jik} + \overline{\nabla}_i \overline{R}_{\nu kjk} \end{aligned}$$

on K . Obviously, $|A_\lambda|^2 \geq \frac{1}{n}|H_\lambda|^2 \geq \frac{1}{n}\delta^2$ on \overline{K} by (3.2), then there is a positive constant C_0 depending only on $n, \delta, |R|$ and $|DR|$ on Ω such that

$$(3.4) \quad \Delta(h_{ij} + \gamma H_\lambda) \geq \langle \lambda E_{n+1}, \nabla(h_{ij} + \gamma H_\lambda) \rangle - (|A_\lambda|^2 + \overline{Ric}(\nu, \nu))(h_{ij} + \gamma H_\lambda) - C_0|A_\lambda|$$

on K . Here $|R|^2 = \sum_{i,j,k,l} |R_{ijkl}|^2$ and $|DR|^2 = \sum_{i,j,k,l,m} |DR_{ijkl,m}|^2$.

Lemma 3.1. *There is a positive constant $\gamma_\lambda^* \geq 1$ depending only on $n, \delta, |R|, |DR|$ on Ω and $\inf_{\partial K} (|A_\lambda|H_\lambda^{-1})$ such that*

$$(3.5) \quad -\frac{1}{\gamma_\lambda^*}H_\lambda \leq |A_\lambda| \leq -\gamma_\lambda^*H_\lambda \quad \text{on } \overline{K}.$$

Proof. Let $\kappa_1 \geq \kappa_2 \cdots \geq \kappa_n$ be the principal curvatures of S_λ . Note that $\kappa_1 = \sup_{|\xi|=1} A_\lambda(\xi, \xi)$, then κ_1 is a continuous function on S_λ . Further, for any $\gamma, \tilde{\gamma} \in \mathbb{R}$,

$$\sup_K (\kappa_1 + \gamma H_\lambda) \leq \sup_K (\kappa_1 + \tilde{\gamma} H_\lambda) + \sup_K ((\gamma - \tilde{\gamma})H_\lambda),$$

which implies that $\sup_K (\kappa_1 + \gamma H_\lambda)$ is also a continuous function on $\gamma \in \mathbb{R}$. There is a constant γ_0 depending on $\inf_{\partial K} (|A_\lambda|H_\lambda^{-1})$ such that

$$\sup_{\partial K} (\kappa_1 + \gamma_0 H_\lambda) = 0.$$

If $\gamma_0 < 0$, we reset $\gamma_0 = 0$. Then we choose a constant γ_1 such that

$$\sup_K (\kappa_1 + \gamma_1 H_\lambda) = -1.$$

We assume $\gamma_1 > \gamma_0 + \frac{1}{\delta}$, or else we complete the proof. By $H_\lambda \leq -\delta$, on ∂K we have

$$(3.6) \quad \kappa_1 + \gamma_1 H_\lambda = \kappa_1 + \gamma_0 H_\lambda + (\gamma_1 - \gamma_0)H_\lambda \leq (\gamma_1 - \gamma_0)H_\lambda \leq -(\gamma_1 - \gamma_0)\delta < -1.$$

Hence $\kappa_1 + \gamma_1 H$ attains its maximum at some point x_0 in the interior of K . Choose a local orthonormal frame $\{e_i\}$ near x_0 in Σ which is normal at x_0 , and denote $h_{ij} = h(e_i, e_j)$ as mentioned before. Let $\xi = \sum_i \xi_i e_i|_{p_0}$ be a unit eigenvector of the second fundamental form corresponding to the eigenvalue $\kappa_1(x_0)$ at the point x_0 , namely, $h(\xi, \xi) = \kappa_1(x_0)$. Then the smooth function $\hat{\kappa}_1 \triangleq \sum_{i,j} h_{ij}|_x \xi_i \xi_j$ attains the maximum $\kappa_1(x_0)$ at x_0 in a neighborhood of x_0 . From (3.4), we obtain

$$(3.7) \quad \Delta(\hat{\kappa}_1 + \gamma H_\lambda) \geq \langle \lambda E_{n+1}, \nabla(\hat{\kappa}_1 + \gamma H_\lambda) \rangle - (|A_\lambda|^2 + \overline{Ric}(\nu, \nu))(\hat{\kappa}_1 + \gamma H_\lambda) - C_0|A_\lambda|.$$

By maximum principle for (3.7), at x_0 we have

$$(3.8) \quad 0 \geq -(|A_\lambda|^2 + \overline{Ric}(\nu, \nu))(\kappa_1 + \gamma_1 H_\lambda) - C_0|A_\lambda| = |A_\lambda|^2 + \overline{Ric}(\nu, \nu) - C_0|A_\lambda|.$$

Let $c_0 = \min \{0, \inf_{|\xi|=1, x \in \Omega} Ric|_x(\xi, \xi)\}$. Then (3.8) implies that at x_0

$$(3.9) \quad |A_\lambda| \leq \frac{C_0}{2} + \sqrt{\frac{C_0^2}{4} - c_0} \leq C_0 + \sqrt{-c_0}.$$

On the other hand, by (3.2) at x_0 one has

$$(3.10) \quad -1 = \kappa_1 + \gamma_1 H_\lambda \leq |A_\lambda| + \gamma_1 H_\lambda \leq |A_\lambda| - \gamma_1 \delta.$$

Combining (3.9)(3.10) and the assumption $\gamma_1 > \gamma_0 + \frac{1}{\delta}$, we obtain

$$(3.11) \quad \gamma_1 \leq \gamma_0 + \frac{1}{\delta} (C_0 + \sqrt{-c_0} + 1).$$

According to the definition of γ_1 and κ_i , $\kappa_1 + \gamma_1 H_\lambda \leq -1 < 0$ on \overline{K} , which implies that

$$(3.12) \quad \kappa_n = H_\lambda - \sum_{i=1}^{n-1} \kappa_i \geq H_\lambda - (n-1)\kappa_1 \geq (1 + (n-1)\gamma_1) H_\lambda.$$

Hence we complete the proof. \square

Due to

$$(3.13) \quad \begin{aligned} & \left\langle \overline{\nabla}_{\partial_{x_i} + \partial_i u_\lambda E_{n+1}} (\partial_{x_j} + \partial_j u_\lambda E_{n+1}), \frac{-Du_\lambda + E_{n+1}}{\sqrt{1 + |Du_\lambda|^2}} \right\rangle \\ &= \left\langle D_{\partial_{x_i}} \partial_{x_j}, \frac{-Du_\lambda + E_{n+1}}{\sqrt{1 + |Du_\lambda|^2}} \right\rangle + \partial_{x_i} \partial_{x_j} u_\lambda \left\langle E_{n+1}, \frac{-Du_\lambda + E_{n+1}}{\sqrt{1 + |Du_\lambda|^2}} \right\rangle \\ &= (\partial_{x_i} \partial_{x_j} u_\lambda - \langle D_{\partial_{x_i}} \partial_{x_j}, Du_\lambda \rangle) \frac{1}{\sqrt{1 + |Du_\lambda|^2}} = \frac{(u_\lambda)_{i,j}}{\sqrt{1 + |Du_\lambda|^2}}, \end{aligned}$$

we have

$$(3.14) \quad |A_\lambda|^2 = \sum_{i,j,k,l} \left(\sigma^{ij} - \frac{\partial^i u_\lambda \partial^j u_\lambda}{1 + |Du_\lambda|^2} \right) \frac{(u_\lambda)_{j,k}}{\sqrt{1 + |Du_\lambda|^2}} \left(\sigma^{kl} - \frac{\partial^k u_\lambda \partial^l u_\lambda}{1 + |Du_\lambda|^2} \right) \frac{(u_\lambda)_{l,i}}{\sqrt{1 + |Du_\lambda|^2}}.$$

Now let's show the main theorem.

Theorem 3.2. *Let $\mathcal{M} : t \in [0, \infty) \mapsto M_t$ be a mean curvature flow starting from a mean convex, smooth hypersurface in an n -dimensional complete smooth manifold Σ . If $\lim_{t \rightarrow \infty} (\cup_{s > t} M_s)$ (maybe empty) is a smooth hypersurface, then all the singularities of \mathcal{M} have convex type.*

Proof. Let v be a viscosity solution to (3.1) on $\Omega \setminus \Omega_\infty$, then $|Dv| > 0$ on $K \setminus \mathcal{S}$. From (3.14), H_λ converges to $\text{div}_\Sigma \left(\frac{Dv}{|Dv|} \right)$, and

$$(3.15) \quad \begin{aligned} |A_\lambda|^2 &= \sum_{i,j,k,l} \left(\sigma^{ij} - \frac{\partial^i U_\lambda \partial^j U_\lambda}{\lambda^{-2} + |DU_\lambda|^2} \right) \left(\sigma^{kl} - \frac{\partial^k U_\lambda \partial^l U_\lambda}{\lambda^{-2} + |DU_\lambda|^2} \right) \frac{(U_\lambda)_{j,k} (U_\lambda)_{l,i}}{\lambda^{-2} + |DU_\lambda|^2} \\ &\rightarrow |A_\infty|^2 \triangleq \sum_{i,j,k,l} \left(\sigma^{ij} - \frac{\partial^i v \partial^j v}{|Dv|^2} \right) \frac{v_{j,k}}{|Dv|} \left(\sigma^{kl} - \frac{\partial^k v \partial^l v}{|Dv|^2} \right) \frac{v_{l,i}}{|Dv|} \quad \text{as } \lambda \rightarrow \infty \end{aligned}$$

on $K \setminus \mathcal{S}$ smoothly. Here $-\operatorname{div}_\Sigma \left(\frac{Dv}{|Dv|} \right)$ and $|A_\infty|^2$ are the mean curvature and the square norm of the second fundamental form for the level set of v in $K \setminus \mathcal{S}$, respectively. Since $\partial K \cap \overline{\mathcal{S}} = \emptyset$, we conclude that $\inf_{\partial K} (|A_\lambda| H_\lambda^{-1})$ is uniformly bounded for any $\lambda \geq 1$, and then γ_λ^* in Lemma 3.1 is bounded by an absolute constant γ^* independent of $\lambda \geq 1$. Namely, by Lemma 3.1 we have

$$-\frac{1}{\gamma^*} H_\lambda \leq |A_\lambda| \leq -\gamma^* H_\lambda \quad \text{on } \overline{K}.$$

Hence we obtain that

$$(3.16) \quad -\frac{1}{\gamma^*} \operatorname{div}_\Sigma \left(\frac{Dv}{|Dv|} \right) \leq |A_\infty| \leq -\gamma^* \operatorname{div}_\Sigma \left(\frac{Dv}{|Dv|} \right) \quad \text{on } K \setminus \mathcal{S}.$$

According to appendix B in [18], we complete the proof. \square

(i) Assume that Σ has nonnegative Ricci curvature in Theorem 3.2. From (2.6), we have

$$(3.17) \quad \Delta \langle E_{n+1}, \nu \rangle = -\langle E_{n+1}, \nabla H \rangle - (|A|^2 + \overline{\operatorname{Ric}}(\nu, \nu)) \langle E_{n+1}, \nu \rangle.$$

Let $S_{\lambda, \alpha}$ be a smooth graph with the graphic function $u_{\lambda, \alpha}$ satisfying (2.11). Combining (2.5), one has

$$(3.18) \quad \Delta \langle E_{n+1}, \nu \rangle = \lambda \eta'_\alpha \langle E_{n+1}, \nabla \langle E_{n+1}, \nu \rangle \rangle - (|A|^2 + \overline{\operatorname{Ric}}(\nu, \nu) - \lambda \eta''_\alpha |\nabla u_{\lambda, \alpha}|^2) \langle E_{n+1}, \nu \rangle.$$

Then by maximum principle for the above equation we have

$$\sup_\Omega \sqrt{1 + |Du_{\lambda, \alpha}|^2} \leq \sup_{\partial\Omega} \sqrt{1 + |Du_{\lambda, \alpha}|^2}.$$

Combining the estimate (2.18), $\frac{1}{\lambda+1} |Du_{\lambda, \alpha}|$ is uniformly bounded on Ω independent of $\lambda, \alpha > 0$ as well as $\frac{1}{\lambda+1} u_{\lambda, \alpha}$. Hence the graph u_λ is a bounded graph with $u_\lambda = \lim_{\alpha \rightarrow \infty} u_{\lambda, \alpha}$. Since $\frac{1}{\lambda} u_\lambda$ converges to v as $\lambda \rightarrow \infty$ on any compact set Q in $\Omega \setminus \Omega_\infty$, we get that v is bounded on Q by a constant independent of Q . Hence the mean curvature flow \mathcal{M} in Theorem 3.2 must vanish in finite time.

(ii) If Σ is simply connected with nonpositive sectional curvature in Theorem 3.2, then we claim

$$(3.19) \quad \sup_{t \in (0, \infty)} \left((1+t)^{-1} \sup_{x \in \Omega} u_t(x) \right) < \infty.$$

Let's prove it by contradiction. If (3.19) fails, there are sequence $t_i > 0$ and $\alpha_i \rightarrow \infty$ such that $(1+t_i)^{-1} \sup_\Omega u_{t_i, \alpha_i} \rightarrow \infty$ as $i \rightarrow \infty$, where u_{t_i, α_i} is a smooth solution to (2.12) with λ, α replaced by t_i, α_i , respectively. We define $s_i \triangleq \sup_\Omega u_{t_i, \alpha_i}$ and $\hat{u}_{t_i} = s_i^{-1} u_{t_i, \alpha_i}$, then

$$(3.20) \quad \operatorname{div}_\Sigma \left(\frac{D\hat{u}_{t_i}}{\sqrt{s_i^{-2} + |D\hat{u}_{t_i}|^2}} \right) + \frac{t_i \eta'_{\alpha_i}}{s_i \sqrt{s_i^{-2} + |D\hat{u}_{t_i}|^2}} = 0.$$

On the other hand, there is a point $x_{t_i} \in \Omega$ such that $\hat{u}_{t_i}(x_{t_i}) = 1$. Let $\rho_{x_{t_i}}(x) = d(x, x_{t_i})$ for any $x \in \Omega$, then $\rho_{x_{t_i}}^2$ is smooth on Σ . By Hessian comparison theorem, we have

$$\Delta_\Sigma \rho_{x_{t_i}}^2 \geq 2n.$$

Set $\Lambda = 2\text{diam}(\Omega) > 0$. Note $(1 + t_i)^{-1}s_i \rightarrow \infty$ as $i \rightarrow \infty$. Hence for sufficiently large $i > 0$

$$\begin{aligned}
 (3.21) \quad & \text{div}_\Sigma \left(\frac{D \left(\frac{1}{2} - \Lambda^{-2} \rho_{x_{t_i}}^2 \right)}{\sqrt{s_i^{-2} + \left| D \left(\frac{1}{2} - \Lambda^{-2} \rho_{x_{t_i}}^2 \right) \right|^2}} \right) + \frac{t_i}{s_i \sqrt{s_i^{-2} + \left| D \left(\frac{1}{2} - \Lambda^{-2} \rho_{x_{t_i}}^2 \right) \right|^2}} \\
 & \leq \frac{-\Lambda^{-2} \Delta_\Sigma \rho_{x_{t_i}}^2}{\sqrt{s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2}} + \frac{8\Lambda^{-6} \rho_{x_{t_i}}^2}{\left(s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2 \right)^{\frac{3}{2}}} + \frac{t_i}{s_i \sqrt{s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2}} \\
 & \leq -\frac{2n\Lambda^{-2}}{\sqrt{s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2}} + \frac{8\Lambda^{-6} \rho_{x_{t_i}}^2}{\left(s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2 \right)^{\frac{3}{2}}} + \frac{t_i}{s_i \sqrt{s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2}} \\
 & \leq \frac{-2(n-1)\Lambda^{-2}s_i + t_i}{s_i \sqrt{s_i^{-2} + 4\Lambda^{-4} \rho_{x_{t_i}}^2}} < 0.
 \end{aligned}$$

Let \mathcal{E} be an open set defined by $\{x \in \Omega \mid \widehat{u}_{t_i} > \frac{1}{2} - \Lambda^{-2} \rho_{x_{t_i}}^2\}$. Since $\widehat{u}_{t_i}(x_{t_i}) = 1$ and $\frac{1}{2} - \Lambda^{-2} \rho_{x_{t_i}}^2 > 0 = \widehat{u}_{t_i}$ on $\partial\Omega$, then $\widehat{u}_{t_i} - \frac{1}{2} + \Lambda^{-2} \rho_{x_{t_i}}^2 = 0$ on $\partial\mathcal{E}$. Analog to (2.14), $\widehat{u}_{t_i} - \frac{1}{2} + \Lambda^{-2} \rho_{x_{t_i}}^2$ attains its maximum on \mathcal{E} at the boundary $\partial\mathcal{E}$ by the maximum principle for (3.20) and (3.21). So we get a contradiction as $\widehat{u}_{t_i} - \frac{1}{2} + \Lambda^{-2} \rho_{x_{t_i}}^2 = 0$ on $\partial\mathcal{E}$, and the claim (3.19) holds.

So $(1 + t)^{-1} \sup_\Omega |u_t|$ is uniformly bounded independent of $t > 0$, which implies that v is bounded and the mean curvature flow \mathcal{M} in Theorem 3.2 must vanish in finite time.

Therefore, from Theorem 3.2 we can get the following corollary.

Corollary 3.3. *Let $\mathcal{M} : t \in [0, \infty) \mapsto M_t$ be a mean curvature flow starting from a mean convex, smooth hypersurface in an n -dimensional complete smooth manifold Σ . If either Σ has nonnegative Ricci curvature or Σ is simply connected with nonpositive sectional curvature, then all the singularities of \mathcal{M} have convex type.*

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